
Differential Equations

Math 341 Fall 2009
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MWF 2:30-3:25pm Fowler 110
<http://faculty.oxy.edu/ron/math/341/09/>

Worksheet 13: Friday October 9

TITLE Euler's Method for Systems of ODEs

CURRENT READING Blanchard, 2.4

Homework Assignments due Friday October 16

Section 2.2: 7, 8, 10, 24, 25.

Section 2.3: 3, 4, 7, 11.

Section 2.4: 2, 4.

Chapter 2 Review: 2, 10, 11, 13, 14, 19, 20, 28, 30.

SUMMARY

It's baaack! We'll look at how to use Euler's Method for estimating solutions to systems of ODEs, i.e. $\frac{d\vec{x}}{dt} = \vec{F}(\vec{x})$.

1. Euler's Method for Systems

The algorithm for generating approximate solutions to the ODE $\frac{d\vec{x}}{dt} = \vec{F}(\vec{x})$ with initial condition $\vec{x}(0) = \vec{x}_0$ is

$$\vec{x}_{new} = \vec{x}_{old} + \vec{F}(\vec{x}_{old})\Delta t$$

EXAMPLE

A lot of the time the systems we will be looking at are systems of two ODEs, so in the case the IVP looks like

$$\begin{aligned}\frac{dx}{dt} &= f(x, y), & x(0) &= x_0 \\ \frac{dy}{dt} &= g(x, y), & y(0) &= y_0\end{aligned}$$

The Euler's Method algorithm for a system of two ODEs looks like

$$\begin{aligned}x_{new} &= x_{old} + f(x_{old}, y_{old})\Delta t \\ y_{new} &= y_{old} + g(x_{old}, y_{old})\Delta t\end{aligned}$$

Exercise

Consider the system $\frac{dx}{dt} = x + y$; $\frac{dy}{dt} = 4x - 2y$. Starting at $(x, y) = (1, 0)$ and $\Delta t = 0.5$ let's take two "Euler steps" to approximate the solution curve through this point.

In *Worksheet #10* we were introduced to the Lotka-Volterra model of predator-prey populations.

$$\begin{aligned}\frac{dR}{dt} &= 2R - 1.2RF \\ \frac{dF}{dt} &= -F + 0.9RF\end{aligned}$$

GROUPWORK

Let's use Euler's Method with a $\Delta t = 1$ and the table below to estimate the population of rabbits and foxes after 3 time-steps, starting with $R(0) = 1$, $F(0) = 1$

t	R	F	R'	F'	ΔR	ΔF	Δt

Clearly, the most efficient way to do this would be to use a computer. Go to the computers and look at the spreadsheet `PredatorPrey.xls` on the S-drive and verify (and extend) your calculations.