
Linear Systems

Math 214 Spring 2007
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Fowler 110 MWF 2:30pm - 3:25pm
<http://faculty.oxy.edu/ron/math/214/07/>

Class 29: Wednesday April 11

TITLE Projection Matrices and Orthogonal Diagonalization

CURRENT READING Poole 5.4

Summary

How to find the projection matrix for projection onto a subspace.

Homework Assignment

HW #27: Poole, Section 5.4: 1,6,7,8,9,11,12,13,14,22,23. EXTRA CREDIT 25.

1. Recalling Projection of a Vector onto Another Vector

For any vectors \vec{u} and \vec{v} where $\vec{u} \neq 0$ then the **projection of \vec{v} onto \vec{u}** is the vector $\text{proj}_{\vec{u}}(\vec{v})$ defined by:

$$\text{proj}_{\vec{u}}(\vec{v}) = \left(\frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \right) \vec{u} = \left(\frac{\vec{u}^T \vec{v}}{\vec{u}^T \vec{u}} \right) \vec{u}$$

(Since $\vec{a} \cdot \vec{b} = \vec{a}^T \vec{b} = \vec{b}^T \vec{a}$)

2. Projecting a Vector Onto A Subspace

What are the projections of $\vec{b} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$ onto

(a) the z -axis, i.e. $\text{span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$?

(b) the xy -plane, i.e. $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$?

We can find P , a projection matrix, which finds the vector $\vec{p} = P\vec{b}$ which is the projection of \vec{b} onto a vector space (e.g. the z axis, the xy -plane) spanned by a given basis \mathcal{W} where $\vec{p} = \text{proj}_{\mathcal{W}}(\vec{b})$.

Consider $P_1 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ and $P_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$. Do these matrices do what we want them to?

Note that the xy -plane is the column space of a matrix A , $\text{col}(A)$ where A is $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$, a matrix whose columns are a basis for the subspace consisting of the xy -plane.

Also note that the z -axis is the column space of the matrix $A = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

In general, we are trying to find the projection of a vector \vec{b} onto the column space of any $m \times n$ matrix (or the span of a given basis for a vector space).

3. Computing The Projection Matrix

Let's look more closely at that projection formula again:

$$\begin{aligned}\text{proj}_{\vec{u}}(\vec{v}) &= \left(\frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \right) \vec{u} \\ &= \left(\frac{\vec{u}^T \vec{v}}{\vec{u}^T \vec{u}} \right) \vec{u} \\ &= \frac{(\vec{u}^T \vec{v}) \vec{u}}{\vec{u}^T \vec{u}} \\ &= \frac{\vec{u}(\vec{u}^T \vec{v})}{\vec{u}^T \vec{u}} \\ &= \frac{(\vec{u}\vec{u}^T) \vec{v}}{\vec{u}^T \vec{u}} \\ &= \left(\frac{\vec{u}\vec{u}^T}{\vec{u}^T \vec{u}} \right) \vec{v} \\ \text{proj}_{\vec{u}}(\vec{v}) &= P\vec{v}\end{aligned}$$

So the projection matrix P for projecting a vector \vec{v} onto a vector \vec{u} is given by $P = \frac{\vec{u}\vec{u}^T}{\vec{u}^T \vec{u}}$.

Exercise

Use the above formula to find the projection matrix for the projection of the vector $\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$ onto the z -axis.

EXAMPLE

Let's change the formula to find the projection matrix onto the subspace spanned by $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$,
i.e. the xy -plane.

So the projection matrix P for projecting a vector \vec{v} onto a subspace equal to the $\text{col}(A)$ is given by $P = A(A^T A)^{-1} A^T$.

Exercise

Find the Projection matrix P which computes the projection of a vector \vec{v} onto the subspace \mathcal{W} where \mathcal{W} is the plane $x - y + 2z = 0$. Use your answer to obtain the projection of $\begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}$ onto \mathcal{W} . After doing that, we can also find the projection of $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ onto \mathcal{W} without doing much work. Why?

4. Orthogonal Diagonalization**DEFINITION**

A square matrix A is **orthogonally diagonalizable** if there exists an orthogonal matrix Q and a diagonal matrix D such that $Q^T A Q = D$ (or $A = Q D Q^T$.)

EXAMPLE

Let's show the matrix $A = \begin{bmatrix} 1 & 2 \\ 2 & -2 \end{bmatrix}$ is orthogonally diagonalizable.

Theorem 5.20

A real square matrix is symmetric IF and ONLY IF it is orthogonally diagonalizable. This result is known as **The Spectral Theorem**.

DEFINITION

The **spectrum** of a matrix is the set of all eigenvalues of the matrix. The **spectral decomposition** of a matrix A is the expression $A = \sum_{i=1}^n \lambda_i \vec{q}_i \vec{q}_i^T$ where $\vec{q}_1, \vec{q}_2, \vec{q}_3, \dots, \vec{q}_n$ are the columns of the orthogonal matrix Q .

$$\begin{aligned}
 A &= QDQ^T \\
 &= \begin{bmatrix} \vec{q}_1 & \vec{q}_2 & \vec{q}_3 & \dots & \vec{q}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 & 0 \\ 0 & 0 & \lambda_3 & 0 & 0 \\ 0 & 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & 0 & \lambda_n \end{bmatrix} \begin{bmatrix} \vec{q}_1^T \\ \vec{q}_2^T \\ \vec{q}_3^T \\ \vdots \\ \vec{q}_n^T \end{bmatrix} \\
 &= \begin{bmatrix} \lambda_1 \vec{q}_1 & \lambda_2 \vec{q}_2 & \lambda_3 \vec{q}_3 & \dots & \lambda_n \vec{q}_n \end{bmatrix} \begin{bmatrix} \vec{q}_1^T \\ \vec{q}_2^T \\ \vec{q}_3^T \\ \vdots \\ \vec{q}_n^T \end{bmatrix} \\
 &= \lambda_1 \vec{q}_1 \vec{q}_1^T + \lambda_2 \vec{q}_2 \vec{q}_2^T + \dots + \lambda_n \vec{q}_n \vec{q}_n^T = \sum_{i=1}^n \lambda_i \vec{q}_i \vec{q}_i^T
 \end{aligned}$$

Does this expression look familiar? Each of the expressions $\vec{q}_i \vec{q}_i^T$ are rank 1 matrices which represent the projection matrix for projecting onto the 1-dimension space spanned by each \vec{q}_i . (Recall $\vec{q}_i^T \vec{q}_i = 1$). The above expression is thus sometimes known as the **projection form of the Spectral Theorem**.

Exercise

Let's find the spectral decomposition of the matrix $A = \begin{bmatrix} 1 & 2 \\ 2 & -2 \end{bmatrix}$.